# Scikit-decide

The Reinforcement Learning, Planning & Scheduling library for engineers and researchers





Université Fédérale

Toulouse Midi-Pyrénées



### Agenda

- Rocket presentation of scikit-decide (10 mn)
- Hands-on demonstrations:
  - Reinforcement Learning on control problems (10 mn)
  - Planning in mazes (10 mn)
  - Scheduling for Resource Constrained Project Scheduling Problems (10 mn)
- A glimpse into industrial use cases and research projects supporting the development of scikit-decide (5 mn)
- Q&A (15 mn)



# Scikit-decide: An AI toolbox for Reinforcement Learning, Automated Planning and Scheduling

- Framework for **decision making** initiated by Airbus
- Developed with support and expertise in AI decision-making from the Australian National University
- Focus on **problem solving**, no need for end-users to be algorithmic experts
- Extensible architecture with domain & algorithm catalog
- Open sourced:

https://github.com/airbus/scikit-decide





# Scikit-decide: catalog of domains/solvers

#### Domains (problems definition, engineering knowledge)

- Airbus domains (proprietary)
- Academic domains
- Bindings to existing domain libraries (e.g. OpenAl Gym)...

#### Solvers (algorithms)

- Search techniques
- Reinforcement Learning
- Scheduling & Routing
- Academic contributions (ANU)
- Bindings to existing solver libraries (e.g. Stable Baselines, RLlib, minizinc)...

#### https://github.com/airbus/scikit-decide



Bring algorithms to engineers

common high-level interface







### Scikit-decide: open-source standards

Base template

Domain R POMDPDomai

Agent: Mult

Constraints:

Environment

Dynamics:

Events:

Goals:

Initialization:

- **Easy install** (Python & C++ parts) via pre-compiled wheels
- Documentation (guide & reference)
- **Examples**, incl. online tutorial notebooks embedded in documentation
- **Code generators** for quick start (domains & solvers)
- Unit/Integration tests
- CI/CD



PipeParallelDomain

Constrained

UnrestrictedActions

MultiAgentRLDomain StatelessSimulatorDomain

ShmParallelDomain

Finetune characteristics (optional)

GoalPOMDPDomain DeterministicPlanningDomain

UncertainInitialized DeterministicInitialized

EnumerableTransitions DeterministicTransitions

Gym environment with scikit-decide tutorial: Continuous Mountain Car

🞧 see Github 👔 🤗 launch binder g

In this notebook we tackle the continuous mountain car problem taken from OpenAI Gyme , a toolkit for developing environments, usually to be solved by Reinforcement Learning (RL) algorithms.

Continuous Mountain Car, a standard testing domain in RL, is a problem in which an under-powered car must drive up a steep hill.





### Hands-on demonstrations

- Reinforcement Learning on control problems
- Planning in mazes
- Scheduling for Resource Constrained Project Scheduling Problems

# Scikit-decide: industrial (Airbus) use cases



Dynamic Probabilistic Flight Planning (Airbus use case) Reduce fuel margin to 0-1% with 99% empirical confidence, save 1% fuel burn on average



Satellite Mission Planning (Airbus Defence & Space use case)

Image delivery delays reduced by 25% compared with simple operator baseline



Reinforcement Learning & Genetic Programming for aircraft control problems (ATTOL use case)

Manufacturing Tasks Scheduling with explanations and natural language interaction, taking into account employee multi-skills and stochastic disruption events Support the development of new control laws, support autonomous taxiing

Average of 11% reduction of schedule makespan compared with industrial SoA in nominal conditions; 2.6% reduction disrupted situations compared to hand-written adaptation rules



#### Academic research ecosystem





### Join the scikit-decide community on github!

# https://github.com/airbus/scikit-decide